Autonics

Ø50mm Shaft type Magnetic Multi-turn **Absolute Rotary Encoder** MGAM50S SERIES

INSTRUCTION MANUAL





Thank you for choosing our Autonics product. Please read the following safety considerations before use.

Safety Considerations

ve all safety considerations for safe and proper product operation to avoid

∆Warning Failure to follow these instructions may result in serious injury or death ▲Caution Failure to follow these instructions may result in personal injury or product dama

The symbols used on the product and instruction manual represent the following ⚠ symbol represents caution due to special circumstances in which hazards may occur

▲ Warning

 Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)

Failure to follow this instruction may result in personal injury, fire, or economic loss

▲ Caution

1. Do not drop water or oil on this unit.

Failure to follow this instruction may result in product damage, or mis-control due to

2. Use the unit within the rated specifications.

Failure to follow this instruction may result in shortening the life cycle of the unit, or product 3. Please check the polarity of power and wrong wiring.

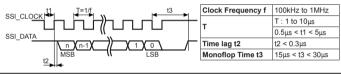
Failure to follow this instruction may result in product damage by burning

Failure to follow this instruction may result in product damage by burning

Ordering Information

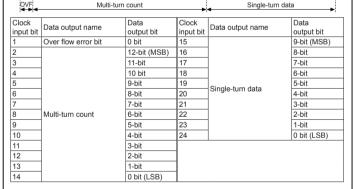
MGAM50S	8	- 10	13	- B	- <u>F</u>	- PN -	- 24
Item	Shaft diameter	Single- turn	Multi-turn	Output code	Rotation direction	Control output	Power supply
50mm Shaft type	Ø8mm	10-bit (1024 -division)		Binary Code	R: Output increases	NPN open	12-24VDC ±5%

Synchronous Serial Interface (SSI) Output Timing Diagram

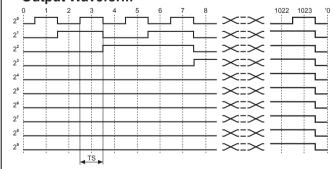


■ Synchronous Serial Interface (SSI) Data Output

*\CVP\M112\M11\M10\M9\M8\M17\M6\M5\M4\M3\M2\M1\M0\\\$9\\\$8\\\$7\\\$6\\\$5\\\$4\\\$3\\\$2\\\$1\\\$0\

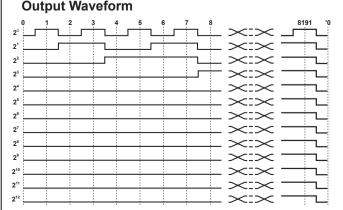


■ Parallel Interface 1024-division Single-Turn Data **Output Waveform**



XTS=0.3515625°±15' **Left waveform is based on the positive logic. (The output waveform of negative logic is in reverse.)

■ Parallel Interface 8192-revolution Multi-Turn Count



 \times Left waveform is based on the positive logic. (The output waveform of negative logic is in reverse.) *The above specifications are subject to change and some models may be discontinued

■ Concifications

Туре				Ø50mm shaft type magnetic multi-turn absolute rotary encoder			
Model				MGAM50S8-1013-B-F-S-24	MGAM50S8-1013-B-F-PN-24		
Resolution Single-turn Multi-turn		Single-turn	1024-division (10-bit)				
			8192-revolution (13-bit)				
Ro	tation limi		n power off *1	±90°			
			eresis	±0.1°			
		Positioning error ^{*2}		±1-bit (LSB: Least Significant -bit)			
		Output code		24-bit, Binary 2 code Binary 2 code			
	Output	Control output		SSI (Synchronous Serial Interface) Line driver • [Low]-Sink current: Max. 20mA, Residual voltage: Max. 0.5VDC • [High]-Sink current: Max20mA, Output voltage: Min. 2.5VDC	Parallel NPN open collector output Sink current: Max. 20mA, Residual voltage: Max. 1VDC		
Ľ		Output signal		Single-turn data, Multi-turn count, over flow alarm (OVF) ^{⊗3}			
specification		Output logic		_	Negative logic output		
		Response time (rise/fall)		_	Max. 1μs (cable: 2m, I sink = 20mA)		
as	Multi-tu	'n	Input level	0-1VDC			
Electrical	count re	set	Input logic	Low Active, OPEN for common use			
<u> </u>	input*4		Input time	Over 100ms			
ш	SSI Clo	ck Inp	out level	5VDC ±5%			
	input In		out frequency	100kHz to 1MHz			
	Max. re:	spons	e frequency	_	30kHz		
	Power supply			12-24VDC ±5% (ripple P-P: max. 5%)			
	Current consumption		umption	Max. 150mA (disconnection of the load)	Max. 100mA (disconnection of the load)		
	Insulation	n res	istance	Over $100M\Omega$ (at 500VDC between	all terminals and case)		
	Dielectr	ic stre	ngth	750VAC 50/60Hz for 1 minute (between	veen all terminals and case)		
	Connec	tion		Axial cable type (cable gland)			
Starting torque		ing torque	Max. 70gf·cm (0.0069N·m)				
	chanical			Max. 80g·cm² (8×10 ⁻⁶ kg·m²)			
spe	ecification	Shaf	t loading	Radial: 10kgf, Thrust: 2.5kgf			
		Max. revolution*5		3000rpm			
Vibration			1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours				
Shock			Approx. Max. 50G				
ment Ambient humidity		nt humidity	35 to 85%RH, storage: 35 to 90%RH				
Protection structure			ire	IP50 (IEC standard)			
Cable				Ø6mm 10-wire, 2m, Shield cable (AWG 28, core diameter: 0.08mm, number of cores: 19, insulator diameter: Ø0.8mm)	Ø6mm 17-wire×2, 2m, Shield cable (AWG 28, core diameter: 0.08mm, number of cores: 17, insulator diameter: Ø0.8mm)		
Accessories				Mounting bracket, coupling			
	proval			CE			
Weight ^{×6}				Approx. 391g (approx. 261g)	Approx. 523g (approx. 393g)		

*1. It calibrates the multi-turn counts by comparing single-turn data before/after power off without counting multi-turn counts when power is off. It shall be used on the condition that no overrated revolution occurred since proper multi-turn counts may not be available if any revolutions occur. over ±90° from the position when power is off

※2: When turning ON/OFF the unit, there may be ±1-bit (LSB) error at present position by hysteresis

33: OVF alarm is ON when multi-turn count is out of counting range (0 to 8191 revolution).
 44: Multi-turn count shall be initialized as ^r0 revolution when multi-turn count reset is input.
 5: In case of Parallel type model, Make sure that Max. response revolution should be lower than or

equal to max, allowable revolution when selecting the resolution.

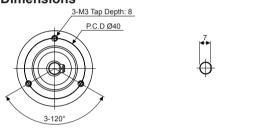
[Max. response revolution (rpm) = $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$]

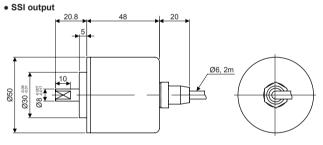
essolution

6: The weight includes packaging. The weight in parenthesis is for unit only

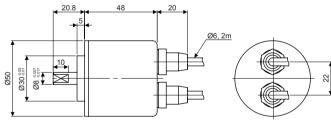
Environment resistance is rated at no freezing or condensation.

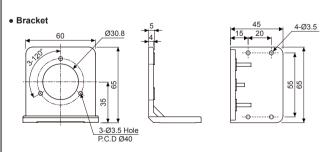
Dimensions

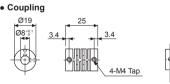


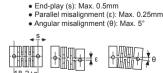


Parallel output









- When mounting the coupling to encoder shaft, if there is combined misalignment (parallel, angular misalignment) between rotating encoder shaft and mate shaft, it may cause encoder and coupling's
- Iffe cycle to be shorten.

 Do not load overweight on the shaft.

 For more information about flexible coupling (ERB Series), please refer to the catalogue.

Functions Multi-turn count reset

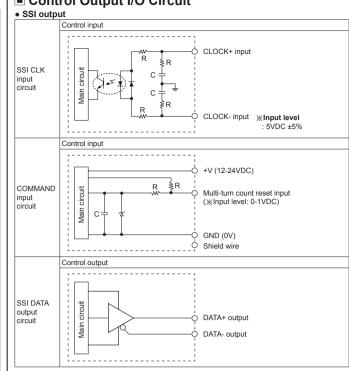
Multi-turn data will be reset as Γ revolution 0_{\perp} when multi-turn count reset cable (light purple) is inputted 0 to 1V (over 100ms)

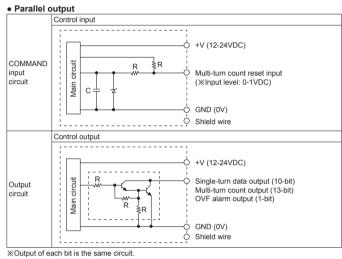
Over flow alarm (OVF)

Using a larm function when multi-turn count is out of rotation ranges (0 to 8191 revolutions).

Over flow alarm is also reset with multi-turn count value when multi-turn count reset signal (light purple) is inputted.

■ Control Output I/O Circuit





※Overload or short may cause circuit break

Connections

SSI output

(unit: mm)

Cable color	Description				
Brown		CLOCK+			
Red	SSI	CLOCK-			
Orange	551	DATA+			
Yellow		DATA-			
Green		Multi-turn count reset			
Blue	COMMAND	N.C.			
Purple	COMMAND	N.C.			
Gray		N.C.			
White	+V (12-24VDC)	•			
Black	GND (0V)				
Shield wire	Signal shield cable (F.G.)				

Multi-turn count cable (Sheath color: Black)			Single-turn data cable (Sheath color: Gray)		
Cable color	Description		Cable color	Description	
Brown		2°	Brown		2°
Red		2 ¹	Red	Single-turn data	2 ¹
Orange		2 ²	Orange		2 ²
Yellow		2 ³	Yellow		2 ³
Green		2^4	Green		2 ⁴
Blue	Multi-turn	2 ⁵	Blue		2 ⁵
Purple	count	2 ⁶	Purple		2 ⁶
Gray	Count	27	Gray		2 ⁷
Pink		2 ⁸	Pink		2 ⁸
Clear		2°	Clear		2 ⁹
Light brown		2 ¹⁰	Light brown	N.C.	
Light yellow	7	211	Light yellow	N.C.	
Light green		2 ¹²	Light green	N.C.	
Light blue	OVF	OVF		N.C.	
Light purple	Multi-turn count r	eset	Light purple	N.C.	
White	N.C.		White	+V (12-24VDC)	
Black	N.C.		Black	GND (0V)	
Shield wire	Signal shield cab	le (F.G.)	Shield wire	Signal shield cable (F.G.)	

※Encoder's metal case and shield cable must be grounded (F.G.) *Do the wiring with care for short since dedicated Driver IC is used for I/O circuit

Cautions During Use

 (i) Handle the unit with care since it consists of precision components.
 (ii) Be careful not to make eccentricity and deflection angle larger, it may shorten the life cycle.
 (iii) Do not put strong impact when inserting coupling into shaft. lease connect shield wire to F.G. terminal.

②Do not connect and cut circuit during power on, or it may cause damage to the unit

When using a switching mode power supply, install the surge absorber on power line for absorbing surge and make the wire as short as possible to avoid noise. 3. Environment

Please do not use this unit with below environment, it may cause malfunction Place where this unit or component may be damaged by strong vibration or impact.
 Place where there are lots of flammable or corrosive gases.
 Place where strong magnet field or electric noise occurs.
 Place where is beyond of rating temperature or humidity.

⑤Place where strong acids or alkali near by.

4. Vibration and Impact

When the strong impact loads on this unit, it may cause an error.

Please use Bracket for more stable unit mounting.
 Please use metallic coupling when the application needs severe acceleration or deceleration

5. Wire connection

ODo not draw the wire with over strength 30N after wiring.

②If wire encoder cable with high voltage line or power cable in the same conduit, it may cause a malfunction or mechanical problem. Please wire it separately or use separated conduit.

*Failure to follow these instructions may result in product damage.

■ Major Products

- Photoelectric Sensors
 Fiber Optic Sensors
 Door Sensors
 SSR/Power Controllers
- Door Side Sensors Counters
- Area Sensors Timers
- Panel Meters
 Tachometer/Pulse (Rate)Meters Pressure Sensors
- Rotary Encoders Display Units Connector/Sockets Sensor Controllers
- Switching Mode Power Supplies
 Control Switches/Lamps/Buzzers
- I/O Terminal Blocks & Cables
- Stepper Motors/Drivers/Motion Controllers
 Graphic/Logic Panels
- Laser Marking System (Fiber, Co₂, Nd: YAG)
 Laser Welding/Cutting System

Autonics Corporation http://www.autonics.com

18, Bansong-ro 513 be Korea, 48002 TEL: 82-51-519-3232

■ E-mail: sales@autonics.cor

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