E88H Series Incremental Ø88mm Hollow Shaft Type

Hollow Shaft Type Ø88mm Incremental Rotary Encoder

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Features

- Ø88mm, Inner diameter of shaft Ø30mm
- No coupling needed with direct installation at elevator winding machine
- Power supply: 5VDC, 15VDC ±5%
- Control output: Complemental output, Line driver output

Please read "Safety Considerations" in operation manual before using.

Ordering Information

E88H	30	- 1024 -	- 2 -	-	15
Series	Shaft inner diameter	Pulses/revolution	Output phase	Control output	Power supply
Ø88mm, hollow shaft type	Ø30mm	1024		No mark: Complemental output L: Line driver output	15: 15VDC ±5% 5: 5VDC ±5%

Specifications

Item			Hollow Shaft Type Ø88mm Incremental Rotary Encoder			
Model			E88H30-1024-2-15 E88H30-1024-6-L-5		Counters	
Re	volution (P	PR)	1,024	·		
	Output phase		A, B phase A, Ā, B, B, Z, Ž phase		(K) Timers	
Electrical specification	Phase difference of output		Output between A and B phase: $\frac{T}{4} \pm \frac{T}{10}$ (T=1cycle of A phase)			
	Control output		 [L]-Load current: max. 15mA, Residual voltage: max. 2.0VDC== [H]-Load current: max. 15mA, Output voltage: min. 10VDC== 	 [L]-Load current: max. 20mA, Residual voltage: max. 0.5VDC [H]-Load current: max20mA, Output voltage: min. 2.5VDC 	(L) Panel Meters (M) Tacho / Speed / Pul:	
	Response time (rise, fall)		Max. 1µs (cable length: 8m, load resistance: $1k\Omega$)	Max. 0.5µs (cable length: 8m, I sink=20mA)	A) Meters	
	Max. response frequency		150kHz			
	Power supply		15VDC== ±5% (ripple P-P: max. 5%)	5VDC== ±5% (ripple P-P: max. 5%)	(N) Display Units	
	Current c	onsumption	Max. 60mA (disconnection of the load)	Max. 50mA (disconnection of the load)		
	Insulation resistance		Over 100MΩ (at 500VDC megger)			
	Dielectric strength		750VAC 50/60Hz for 1 min (between all terminals and case)			
	Connection		Radial cable type			
on Sal	5 Starting torque		Max. 600gf·cm (0.06N·m)			
anic	Moment of inertia		Max. 800g·cm ² (8×10 ⁻⁵ kg·m ²)			
echanical	Shaft loading		Radial: max. 5kgf, thrust: max. 2.5kgf			
[™] Max. allowable revolution ^{*1}		owable revolution*1	3,600rpm			
Vibration			1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours			
Shock			Approx. max. 100G			
_	ironmont	Ambient temp.	-10 to 70°C, storage: -25 to 85°C			
Environment Ambient humi.		Ambient humi.	35 to 85%RH, storage: 35 to 90%RH			
Protection structure		ucture	IP50 (IEC standard)			
Cable			Ø6mm, 6-wire, 8m, shield cable (AWG24, core diameter: 0.16mm, number of cores: 11, insulator out diameter: Ø1mm)	Ø6mm, 8-wire, 8m, shield cable (AWG24, core diameter: 0.08mm, number of cores: 40, insulator out diameter: Ø1mm)	(T) Software	
Accessory			Spring bracket: 2			
Approval			CE (except line driver output model)			
Weight ^{**2}			Approx. 1.49kg (approx. 1.45kg)			

X1: Make sure that max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

[Max. response revolution (rpm)= Max. response frequency × 60 sec] Resolution

%2: The weight includes packaging. The weight in parenthesis is for unit only.

※Environment resistance is rated at no freezing or condensation.



(A) Photoelectric Sensors

(B) Fiber Optic Sensors

NEW

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encode

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature Controllers

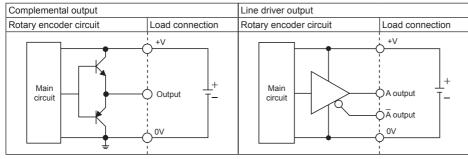
(I) SSRs / Power Controllers

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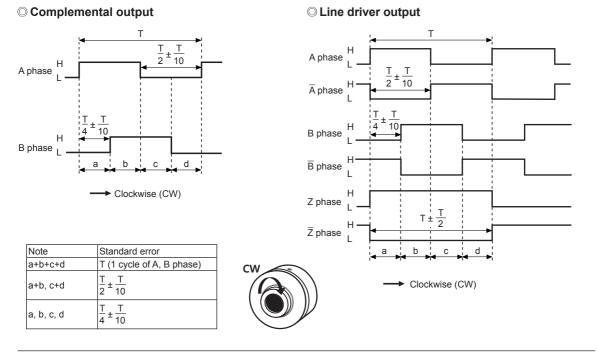
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Control Output Diagram



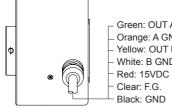
 \times All output circuits of A, \overline{A} , B, \overline{B} , Z, \overline{Z} phase are the same.

Output Waveforms



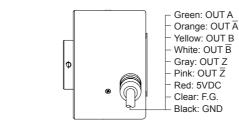
Connections





Green: OUT A Orange: A GND Yellow: OUT B White: B GND

○ Line driver output



*Unused wires must be insulated

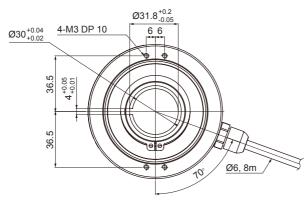
%The metal case and shield cable of encoder should be grounded (F.G.).

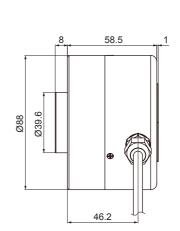
*The output circuit has the dedicated IC and be sure not to short-circuit when wiring the output cables.

XDo not apply tensile strength over 30N to the cable.

Incremental Ø88mm Hollow Shaft Type

Dimensions





(unit: mm) (A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encode

(G) Connectors/ Connector Cables/ Sensor Distribution Boxes/Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

(K) Timers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

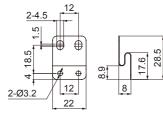
(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software

O Bracket



% Fix the unit by a wrench under 0.15N m of torque.