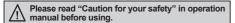
## DIN W48×H48mm, W72×H36mm, W72×H72mm Counter/Timer

### Features

- Available to set 6 digits (0.00001 to 999999) prescale value (4digit: 0.001 to 9999)
- Built-in Modbus communication function (Communication model)
- Available to set the One-Shot output time in 10ms. (0.01sec. to 99.99sec.)
- Increase contact capacity to 5A (CTS, CTM Series)
- Available to set Count Start Point. (Initial value)
- Added BATCH counter function (CTM Series)
- Added Counter Up-1 / Up-2 / Down-1 / Down-2 input modes
- Added Counter TOTAL / HOLD operation modes in the indicator
- Added Timer TOTAL / HOLD / On Time Display operation modes in the
- Added Timer INT2 / NFD / NFD.1 / INTG output modes
- Added Timer range 999.999s / 9999m59 / 99999.9h





## DAQMaster (Comprehensive Device Management Program)

- DAQMaster is comprehensive device management program for convenient management of parameters and multiple device data monitoring.
- Visit our website (www.autonics.com) to download user manual and comprehensive device management program.

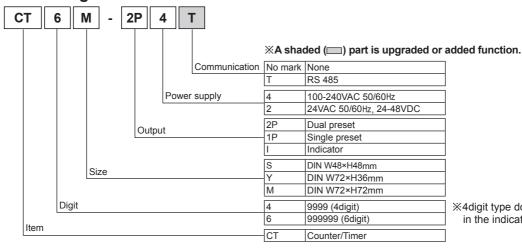
Item	Minimum requirements		
System IBM PC compatible computer with Intel Pentium III or above			
Operations	Microsoft Windows 98/NT/XP/Vista/7		
Memory	256MB+		
Hard disk	1GB+ of available hard disk space		
VGA	Resolution: 1024×768 or higher		
Others	RS-232 serial port(9-pin), USB port		

< DAQMaster screen >

123458



## Ordering Information



X4digit type does not exist in the indicator type.

J-8 **Autonics** 

Series			CTS		CTY	СТМ	Photoelectric Sensors
Digit			4	6	6	6	
	Dual Pr	eset	CT4S-2P□□	CT6S-2P□□	CT6Y-2P□□	CT6M-2P□□	(B) Fiber
Model	Single F		CT4S-1P□□	CT6S-1P□□	CT6Y-1P□□	CT6M-1P□□	Optic
	Single F		_	CT6S-1□□	CT6Y-1	CT6M-1□□	Sensors
5	Single F		11mm	10mm	10mm	13mm	(c)
Digit size	Single F		8mm	7mm	7mm	9mm	Door/Area
Power	AC pow		100-240VAC 50/60				Sensors
Supply	AC/DC		24VAC 50/60Hz, 24				1
Allowable volt			90 to 110% of rated				(D) Proximity
Power	AC pow		Max. 12VA (100-24				Sensors
consumption				50/60Hz), Max. 8W	(24-48VDC)		1
INA/INB Max				Ocps / 1kcps / 5kcps			(E) Pressure
Min. input Counter			Reset signal: Selec				Sensors
Min. input signal width	Timer			Selectable 1ms, 20m	s	INA, INH, RESET, INHIBIT, BATCI RESET: Selectable 1ms, 20ms	(F)
			Selectable voltage	input or No-voltage i	nput	, , , , , , , , , , , , , , , , , , , ,	Rotary Encoders
Input			[Voltage input] Inpu	it impedance is 5.4ks	Ω, 'H' level: 5-30VDC, 'L' level: (	0-2VDC	
•					nce: Max. 1kΩ, Residual voltage		(G)
One-shot out	put			table 0.01s to 99.99			Connectors/ Sockets
		Contact	Dual preset: SPST	(1a) 2EA	Dual preset: SPST (1a) 1	EA, SPDT (1c) 1EA	Sockets
	Without		Single preset: SPD		Single preset: SPDT (1c)		(L)
	com.	Solid state	Dual preset: 1NPN	open collector		Dual preset:3NPN open collector	(H) Temperature
		output	Single preset: 1NP			Single preset:2NPN open collector	
		Contact	Dual preset: SPST			Dual preset: SPST (1a), SPDT (1c	:)
Control		output	Single preset: SPD	T (1c)1EA		Single preset: SPDT (1c)	(I) SSRs / Power
output	com.	Solid state			Dual preset: -	Dual preset:2NPN open collector	Controllers
		output			Single preset:1NPN open co	llector Single preset:2NPN open collector	
	VACOL	Contact	250VAC 5A resistiv	re load	250VAC 3A resistive load	250VAC 5A resistive load	(J)
		output					Counters
	com.	Solid state	30VDC Max. 100m	A Max.			
					100		
Memory retention 10years (When using non-volatile semiconductor memory type)					(K) Timers		
iviernory rete	Repeat error					┞	
	SET err		Payer ON Start May 10 049/ 10 05 acc				(L)
Timer	Voltage		I ower out clart: max: 20.0170 20.00 000				
		ture error	Signal Start: Max. ±0.01% ±0.03 sec				
Insulation res		ture error	Min. 100MΩ (500V	DC Moggar)			(M)
Dielectric stre			2,000VAC 50/60Hz				Tacho / Speed / Pulse
Noise streng		nwer)			th:1us) by the noise simulator		Meters
TVOISE Streng	Mechar		±2kV the square wave noise (pulse width:1µs) by the noise simulator 0.75mm amplitude at frequency of 10 to 55Hz (for 1 min.) in each X, Y, Z direction for 1 hour				
Vibration	Malfunc						(N) Display Units
	Mechan		D.5mm amplitude at frequency of 10 to 55Hz (for 1 min.) in each X, Y, Z direction for 10 min.  300m/s² (approx. 30G) in each X, Y, Z direction for 3 times				
Shock	Malfund		100m/s² (approx. 10G) in each X, Y, Z direction for 3 times				
Relay	Mechan		Min. 10,000,000 operations				(O) Sensor
Life cycle	Electric		Min. 10,000,000 operations				Controllers
Protection st		ai	IP65 (Front panel of				+
1 TOLCOLIOTI SLI	Ambien	<u> </u>	` '	• •			(P) Switching
	tempera		-10 to 55°C, storag	e: -25 to 65°C			Mode Power Supplies
Environment	Ambien						Сарриос
	humidit		35 to 85%RH, stora	age: 35 to 85%RH			(Q) Stepper Motor
A	mamman	<u> </u>	(( 5)				& Drivers
Approval			(€ 6 <b>91</b> 0s		T-		& Controllers
Unit weight			Approx. 159g		Approx. 149g	Approx. 253g	(R)
※Environmer	nt resista	nce is rated	I at no freezing or co	ondensation.			Graphic/ Logic
			n Specifi				Panels
<b>-</b> Com	IIIuII	icatio	ii Speciii	Cation			(S) Field
Protocol		Modbu	ıs RTU (16bit CRC)				Network Devices
Connection r	nethod	RS485					
Application s	tandard	Comp	iance with EIA RS4	85			(T)
	Number of connections 31, it is available to set address 1 to 127					Software	
Communicat		od Half D	uplex				
Synchronous			hronous				
Communicat			max. 800 meter				
Communicat				/38,400bps (Factory	default: 9,600bps)		
Response wa			ms (Factory defaul		· · · / · · · · <del>/ - /</del>		
Start bit	<u> </u>	1-bit (I		*			
Data bit		8-bit (I					

8-bit (Fixed)

None, Even, Odd (Factory default: None)

1, 2-bit (Factory default: 2-bit)

Data bit Parity bit

Stop bit

J-9 **Autonics** 

## Connections

- Connections

RESISTIVE

© CT S-2P 12VDC 100mA RESET OVDC 100mA OUT1 250VAC 5A 250VAC 5A 1 + 1

CT S-1P

12VDC 100MA
INB /INH
INA

0VDC

0VDC

0VDC

100MA

RESET
0VDC
100MA

NO COM NC
250VAC 5A
RESISTIVE LOAD

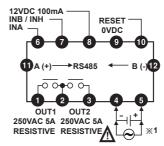
RESISTIVE

© CT6S-I | 12VDC 100mA | RESET | 0VDC | 100mA | 100mA

○ CT6Y-2P□

INB / INH —— 12VDC 100mA Be careful that connections are different between communication model and non-communication model when wiring.

© CT□S-2P□T



© CT S-1P T

12VDC 100mA

INB / INH
INA

0VDC

0VDC

11A (+) → RS485 ← B (-) 12

OUT

0VDC

250VAC 5A

RESISTIVE LOAD

\*1

© CT6S-I T

12VDC 100mA
INB / INH
INA

6 7 8 9 0

11 A (+) → RS485 ← B (-) 12

1 2 3 4 5

250VAC 3A 250VAC 3A STATE OUT
RESISTIVE LOAD RESISTIVE LOAD 30VDC
NC COM NO OUT 100mA

9 9 10 11 2 13
OUT2 OUT1 OUT2

SOLID

250VAC 3A

RESISTIVE LOAD

NC COM NO

100mA

8 9 10 11 12 13

OUT

OUT

INA

INB / INH

12VDC 100mA

SOLID

STATE OUT

30VDC

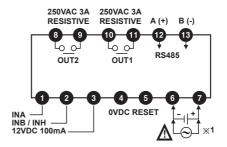
100mA

×1

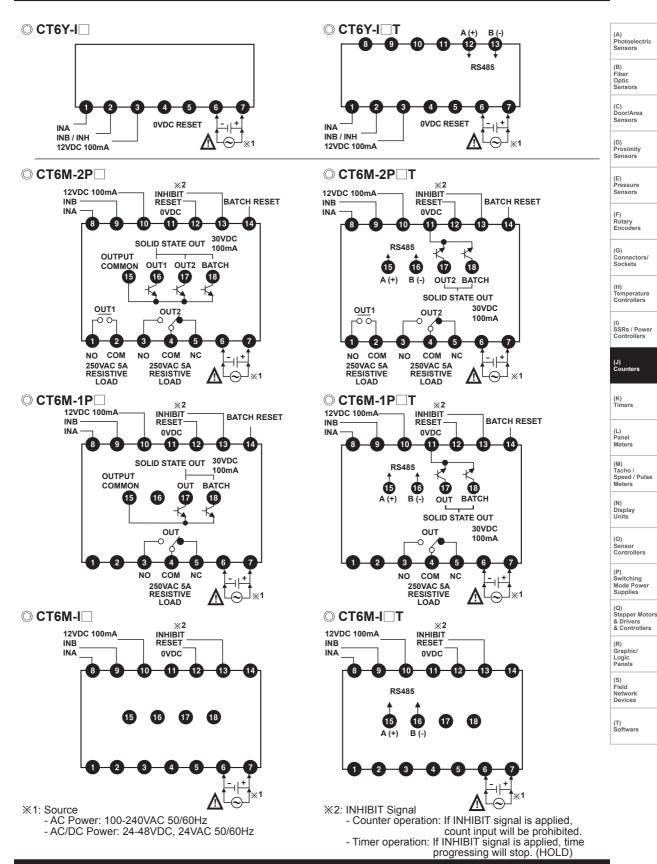
OVDC RESET

 $\odot$ 

© CT6Y-2P□T



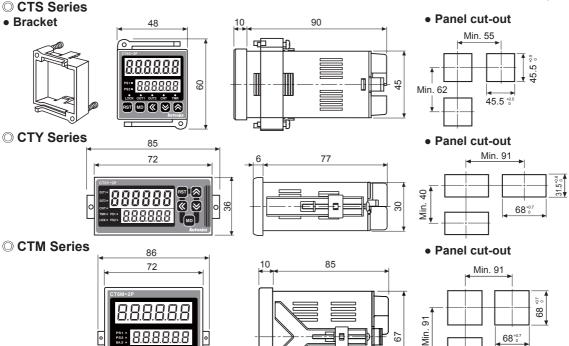
© CT6Y-1P□T SOL ID 250VAC 3A STATE OUT RESISTIVE LOAD 30VDC 100mA A (+) B (-) COM NO RS485 0 -**≰**OUT OUT **0VDC RESET** IΝΑ INB / INH 0 12VDC 100mA





(unit:mm)





## Unit Description

#### CTS Series



## CTY Series 88888 6 2

There are no

PS1, OUT1 LEDs.

There are no PS1, OUT1

OUT2 LEDs

Changed Notice

\*The indicator type does not exist in CT4S model.

## CTM Series



#### 1. Count indicator (Red LED)

- Run mode
- : Count mode-Indicates count value. Timer mode-Indicates time progressing.
- Function setting mode
- : Indicates function setting mode.

#### 2. Preset value indicator (Yellow-Green LED)

- Run mode: Indicates preset value.

- Function setting mode: Indicates setting value1.
- 3. Key Lock: Lights when setting key lock.
- 4. The operation of counter indicator
- 5. The operation of timer indicator
  - TMR LED flashes when the timer is operating. TMR LED lights when the operating time stops

#### 6. Check preset value and display change of it

PS1 LED lights when checking or changing the setting value1. PS2 LED lights when checking or changing the setting value2.

ST BA MD (

Model

CT6M-1P

CT6Y-I

CT6S-I

CT6M-I

CT6Y-1P CT6S-1P PS2→PS

CT4S-1P OUT2→OUT

#### 7. Output (OUT1, OUT2) indicator

OUT1 lights when output1 is on.

OUT2 lights when output2 is on.

#### 8. Reset key

By pressing RST key in Run mode, the count value is initialized and output is returned.

By pressing RST key in BATCH counter mode, BATCH count value resets

### 9. Mode key

- By pressing Mokey for 3sec (parameter setting)/ 5sec (communication) in RUN mode, it moves to function setting mode.
- By pressing 
   Mee key in function setting mode, select function setting mode. By pressing we key over 3 sec., it moves to Run mode.
- By pressing MD key over 1 sec. in function setting checking mode, it moves to Run mode.

#### 10. Set key

- ■: To enter into setting value (PS1, PS2) change status and shift digit of setting value (PS1, PS2).
- To decrease setting value in setting value change mode, change setting value in function setting mode, move down checked value in function setting check mode.
- To increase setting value in setting value change mode, change setting value in function setting mode, move up checked value in function setting check mode. By pressing MD key over 1 sec. in Run mode, enters into function setting check mode.

#### 11. BATCH key

By pressing BA key in run mode to enter into BATCH counter indication mode.

- 12. BATCH output indicator (red LED)
- 13. BATCH setting value checking and changing indicator (yellow-green LED)

Lights when checking and changing BATCH setting value.

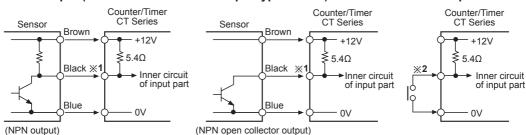
Contact input

Contact input

## **■** Input Connections

### ○ No-voltage input (NPN)

• Solid-state input (Standard sensor: NPN output type sensor)

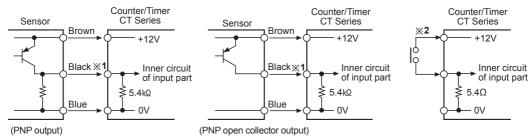


X1: INA, INB/INH, RESET, INHIBIT, BATCH RESET input part

X2: Counting speed: 1 or 30cps setting (Counter)

## O Voltage input (PNP)

• Solid-state input (Standard sensor: PNP output type sensor)

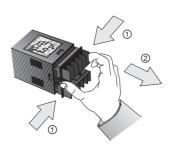


X1: INA, INB/INH, RESET, INHIBIT, BATCH RESET input part

X2: Counting speed: 1 or 30cps setting (Counter)

## ■ Input Logic Selection[No-Voltage Input (NPN)/Voltage Input (PNP)]

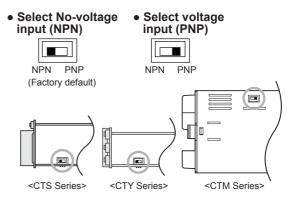
- 1. The power must be cut off.
- 2. Detach the case from the body. (CTS, CTY Series)



\* Case detachment Squeeze toward ① and pull toward ② as shown in picture.

♠ Please check if the power is cut off.

Select input logic by using input logic switch (SW1) inside Counter/Timer.



- 4. Push a case in the opposite direction of 2-2.
- 5. Then apply the power to Counter/Timer.

(A) Photoelectric Sensors

(B) Fiber Optic

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

> (F) Rotary Encoders

Connectors/ Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J)

(K)

L)

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers

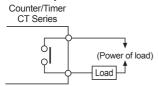
(R) Graphic/ Logic Panels

(S) Field Network Devices

> (T) Software

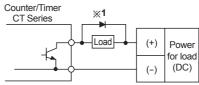
## **■** Output Connections

### Contact output



XUse proper load not to exceed the capacity.

## O Solid-state output



- \*\*Use proper load and power for load not to excess ON/OFF capacity (30VDC Max. 100mA max.) of solid state output.
- XBe sure not to apply reverse polarity of power.
- X1: When using inductive load (Relay etc), surge absorber (Diode, varistor etc) must be connected between both sides of the load.

## **■** Factory Default

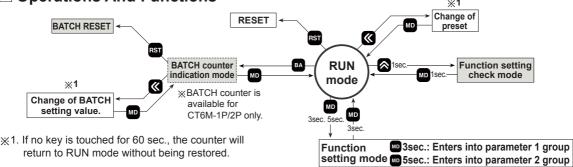
	Parameter	Factory default			
$\vdash$		UP/Down-C [Ud- []			
	Input mode [ all this]	F [F]			
	' '				
	CPS [[P5]	30cps [30]			
	Indication mode (indicator type) [d5P.ā]				
	OUT2 output time [oUt.2]	Hold [Hald]			
١.	OUT1 output time [olde.1]	100ms [00.10]			
Counter	Decimal point [dP]				
l i	Min. reset time [-54]	20ms [20]			
0	Input logic [5+ 6]	NPN [nPn]			
	Prescale decimal point [5 [.d P]	6digit type:, 4digit type:			
	Prescale value [5[L]	6digit type: 1.00000 , 4digit type: 1.000			
	Start Point setting [54 r 4]	000000			
	Counting memory [dRER]	Clear [5L - ]			
	Lock key [Lo[P]	Lock off [LoFF]			
	Preset value 1 (PS1)	1000 [1000]			
	Preset value 2 (PS2)	5000 [5000]			
	Time range [Holle/falle/5EE]	6Digit type: 0.001s-999.999s, 4Digit type: 0.001s-9.999s			
	Up/Down mode [U-d]	UP [up]			
	Indication mode (Indicator type) [d5P.ñ]	TOTAL [LoERL]			
	Memory protection (Indicator type) [dRER]	CLEAR [5Lr]			
	Output mode [all E.n.]	OND [and]			
Timer	OUT2 output time [allt2]	Hold [HoLd]			
=	OUT1 output time [all E 1]	100ms [00.10]			
	Input logic [5+ 6]	NPN [nPn]			
	Input signal time [/ ភ.৮]	20ms [20]			
	Lock key [Lock]	Lock off [Loff]			
	Preset value 1 (PS1)	1000 [1000]			
	Preset value 2 (PS2)	5000 [5000]			
	Communication address [Addr]	01 [00 1]			
ţi	Communication speed [bP5]	9600bps [95]			
isa	Communication parity [Prty]	NONE [nonE]			
l m	Communication stop bit [5 t P]	2 [2]			
Communication	Response waiting time [-54]	20ms [20]			
ŭ	Communication writing [[oñ4]	Enable [EnR]			

## **■** Error Display

Err	or display	Errors	Output status	How to return
	Ε	Failed in data loading for exsiting setting	OFF	Power on again
	PS10 PS20 F	values		,

J-14 Autonics





## Change of preset (Counter/Timer)

• Even if changing the preset value, input operation and output control will continue. In addition, the preset value could be set to 0 and 0 preset value turns ON. According to output mode, preset value could not be set to 0. (When setting to 0, preset value "0" will flash 3 times.)



In Run mode, it enters into the preset value setting mode using & key. 'PS1' LED lights and first digit of preset value flashes



The preset value is set to 'IB□' using ♠, ♠ and ♠ keys, then press ♠ key to enter into the PS2 setting mode.



The preset value is set to '200' using ♠, ♠ and ♠ keys, then press ♠ key to complete PS2 setting and return to Run mode.

X Press key to save set value after changing the setting value. Then, it moves to next parameter or returns to RUN mode. However, if no key is touched for 60 sec., it will return to RUN mode without being saved.

#### Function setting check mode

#### Switching display function in preset indicator

• Setting value 1 (PS1) and setting value 2 (PS2) are displayed each time pressing we key in dual preset model. (In timer, it is available for and, and I, and I output mode.)

#### ○ Reset

• In Run mode or function setting mode, if wey or applying the signal to the RESET terminal on the back side, present value will be initialized and output will maintain off status. When selecting voltage input (PNP), short terminal 10 and 12, or when selecting no-voltage input (NPN), short terminal 11 and 12 to reset.

## ■ BATCH Counter (For CT6M-1P□ □ /CT6M-2P□ □ Model Only)

In BATCH counter indication mode, 'BATCH counter value' is displayed in count indicator and 'BATCH counter setting value' is displayed in preset indicator.

### Change of BATCH setting value

If pressing key in Run mode, it will enter into BATCH counter indication mode.



It enters into settingvalue change mode using key. (BA.S lights, first digit of setting value flashes.)



BATCH value is set to '200' using (a), (a) and (b) keys, then press (b) key to complete BATCH setting value and move to BATCH counter indication mode.

(A) Photoelectric Sensors

(B) Fiber Optic

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G)

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

> (K) Timers

Panel Meters

(M) Tacho / Speed / Pulse Meters

> l) isplay nits

(O) Sensor Controllers

(P) Switching Mode Powe Supplies

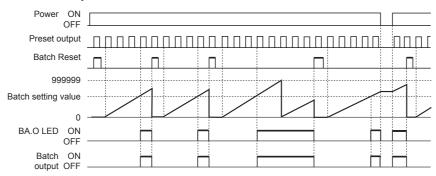
(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software

#### BATCH counter operation



#### BATCH counting operation

- BATCH counting value is increasing until BATCH reset signal applied. BATCH counting value will be circulated when it is over 999999.
  - 1) BATCH counting operation in Counter: Counts the number of reaching setting value of CT6M-1P or reaching dual setting value of CT6M-2P□□
  - 2) BATCH counting operation in Timer: Counts the number of reaching setting time.

(In case of "FLK" output mode, count the number of reaching T.off setting time and T.on setting time.)

#### BATCH output

- If input signal is applied while changing BATCH setting value, counting operation and output control will be performed.
- If BATCH count value equals to BATCH setting value, BATCH output will be ON and maintain ON status until BATCH reset signal is applied.
- When the power is cut off then resupplied in status of BATCH output is ON, BATCH output maintains ON status until BATCH reset signal is applied.

#### BATCH reset input

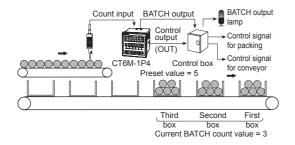
- If pressing reset button or applying the signal to BATCH reset terminal on the back side panel, BATCH counting value will be reset. When selecting voltage input (PNP), short terminals 10 and 14, or when selecting no-voltage input (NPN), short terminals 11 and 14 to reset.
- When BATCH reset is applied, BATCH counting value maintains at 0 and BATCH output maintains in the OFF status.

#### Application of BATCH counter function

#### Counter

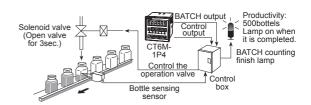
In case, put 5 products in a box then pack the boxes when they reaches to 200.

- Counter preset setting value="5", BATCH setting value="200"
- When the count value of counter reaches to the preset value "5", the control output (OUT) will be on, and at this time the count value of the BATCH counter will be increased by "1". The control box which is received the control output (OUT) repeatedly controls conveyor to move the full box and to place the next empty box for standby. When the BATCH count value reaches to "200", BATCH output will be ON. Then the control box stops conveyor and provides a control signal for packing.

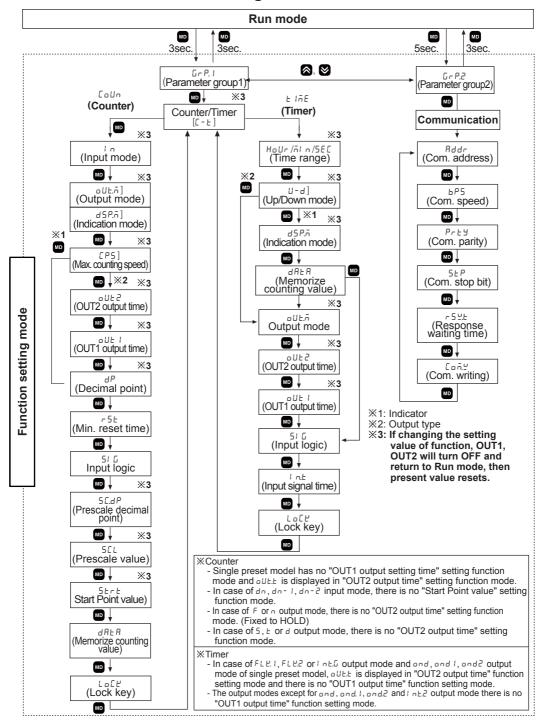


#### Timer

Fills milk into the bottle for 3sec. (setting time) When 500 bottles are filled, BATCH counting finish lamp is turned on. (Setting time: 3sec., BATCH setting value: 500)



## ■ Flow Chart For Function Setting Mode



XIf changing setting value of parameter group1, display value and output will be initialize.

※Press ■ key over 3sec./5sec. in RUN mode to enter into parameter 1 group/ parameter 2 group.

Press key over 3 sec. in function setting mode to return RUN mode.

XInput operation and output control can be set in function setting mode.

※If changing set value of ※3 marked parameters in function setting mode, OUT1 and OUT2 output will be turned OFF and
then the current value is reset.

※Parameter 2 group is not available to non-communication models.

(A) Photoelectric Sensors (C) Door/Area Sensors (D) Proximity (E) Pressure Sensors (F) Rotary Encode (I) SSRs / Power Controllers (M) Tacho / Speed / Pulse Meters (N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

> S) Field Network Devices

Network Devices

Software

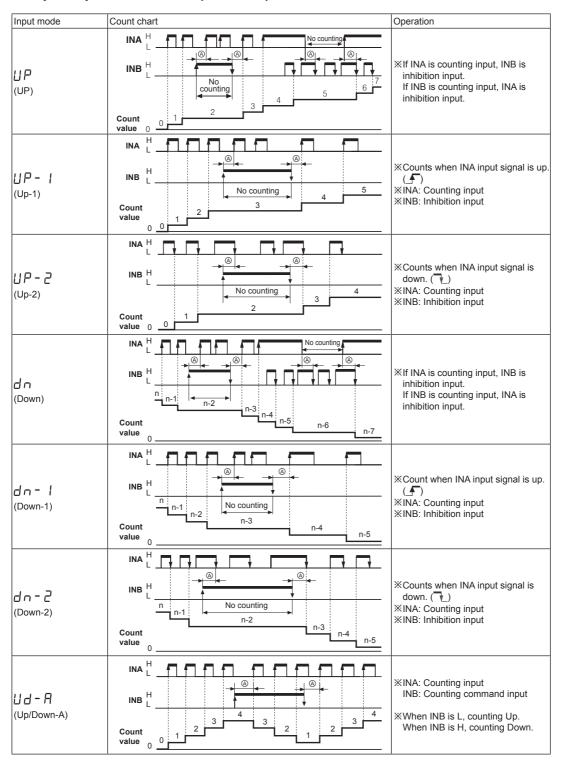
## ■ Parameter Setting (Counter)

(wo key: To select setting mode, ≥ or ≥ key: To change setting value)

0.111	the treat	
Setting mode	How to set	COUNTED
Counter/Timer	©Un ← → El ñE #ConE: C	COUNTER MER
Input mode	Ud-C ←→ UP ←→ UP-1 ←→ UP-2 ←→ dn ←→ dn-1 ←→ dn-1	2 <b>←→</b> Ud- B <b>←→</b> Ud- b
Output mode oUt.ñ Indication mode d5P.ñ	<ul> <li>UP, UP-1, UP-2 or dn, dn-1, dn-2 input mode</li> <li>F ← → n ← E ← r ← P ← P ← P ← P ← P ← P ← P ← P ← P</li></ul>	
Max. counting speed	30 ←→12 ←→52 ←→ 102 ←→1 and it is applied in INA and IN	by one (1:1) duty ratio of INA or INB input signal, B at thesame time. mode, you can choose 1cps, 30cps, 1Kcps.
OUT2 output time	output time value.	one-shot output time. ge: 0.01 to 99.99 sec. appear if F, n output mode is selected.
OUT1 output time	output time value.   *Time range:	one-shot setting time : 0.01 to 99.99 sec., Hold played by pressing <b>③</b> key 4 times.
<b>※1</b> Decimal point dP	• 6digit type     • 4digit type     • will be a set of the se	ecimal point is applied same to counting
Min. reset time	/ ← → ≥0 unit: ms	nal RESET signal width.
Input logic	กคล: No-Voltage input คลค: Voltage input **Check input logic v	value (PNP, NPN).
<b>** 1</b> Prescale decimal point 5C.dP	6digit type     4digit type     **Prescale decimal point setting digit	point position is not set below the decimal s [dP].
Prescale value 501	<ul> <li>③: To shift the flashing digit.</li> <li>③ ②: To change the prescale value.</li> <li>★Setting range of period of the flashing digit.</li> <li>★Gdigit type: 0.000 digit type: 0.001</li> <li>★Refer to page J-2</li> </ul>	001 to 99999.9
Start Point Value	<ul><li>③: To shift the flashing digit.</li><li>⑤ (Adigit type: 0.000 4digit type: 0.000</li></ul>	
Memory protection	ELr ← → rEΓ	
Lock key	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	

- $\ensuremath{\mathbb{X}}$ 1. Explanation of decimal point and prescale decimal point setting
  - Decimal point setting: Set decimal point of the display value on front indicator.
  - Prescale decimal point setting: Set prescale decimal point of counting regardless of decimal point of display value on front indicator.

## **■** Input Operation Mode (Counter)



(A) Photoelectric Sensors

(B) Fiber Optic

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G)

(H) Temperature Controllers

(I) SSRs / Power Controllers

#### (J) Counters

(K) Timers

anel

(M) Tacho / Speed / Pulse

(N) Display Units

> onsor ontrollers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

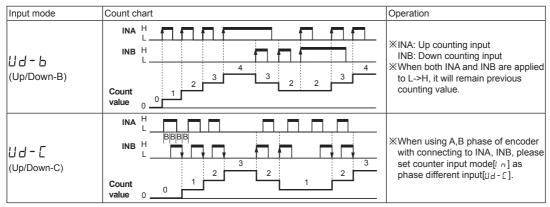
(R) Graphic/ Logic Panels

S) ield letwork

etwork

T) Software

### ■ Input Operation Mode (Counter)



※ (a) signal width should be over min. signal width and (b) signal width should be over a half min. signal width.

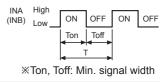
If not, ±1 will occur.

#### \*The meaning of "H" and "L"

	Voltage input (NPN)	No-Voltage input (PNP)
Н	5-30VDC	Short circuit
L	0-2VDC	Open

## \*Min. signal width by counting speed

Mirini. Orginal Wider by					
Counting speed	Min. signal width				
1cps	500ms				
30cps	16.7ms				
1kcps	0.5ms				
5kcps	0.1ms				
10kcps	0.05ms				

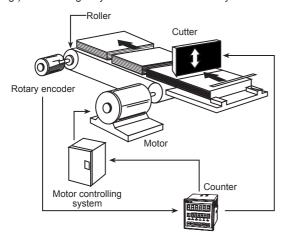


## Prescale Function (Counter)

This function is to set and indicate calculated unit for actual length, liquid measure, position etc. It is called "Prescale value" for measured length, measured liquid, measured position, etc per 1 pulse.

For example, P is the number of pulses per 1 revolution of a rotary encoder and L is the desired length to be measured. Prescale value is [the desired length (L)]/[the number of pulses (P) per 1 revolution of the rotary encoder.]. It is the length per 1 pulse of a rotary encoder.

#### E.g.) Control length by the counter and the rotary encoder



[In case of 22mm diameter (D) of roller connected with the encoder of 1,000 pulse]

• Prescale value =  $\frac{\pi \times \text{Diameter of the roller (D)}}{\text{The number of pulses per}}$ 1 revolution of the encoder

 $= \frac{3.1416 \times 22}{1000}$ = 0.069 mm/pulse

To control conveyor position in 0.1mm, set the decimal point to tenth place[-----] in decimal point setting mode[ $\mathcal{AP}$ ] and set the prescale decimal point to thousandth place[-----] in prescale decimal point setting mode[ $\mathcal{LAP}$ ]. Then set prescale value "0.069" in prescale setting mode [ $\mathcal{LL}$ ].

## Start Point Function (Counter)

This function is that start at initial value set at Start Point [5 + r + ] when on counting mode.

- In case of dn, dn- 1 or dn-2 in timer input mode, it is not available.
- When reset is applied, the present value is initialized to start point.
- After count up in [, r, P, 9 After count up in

J-20 Autonics

(A) Photoelectric Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encode

(I) SSRs / Power Controllers

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(P) Switching Mode Powe Supplies

& Drivers & Controllers

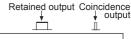
(R) Graphic/ Logic Panels

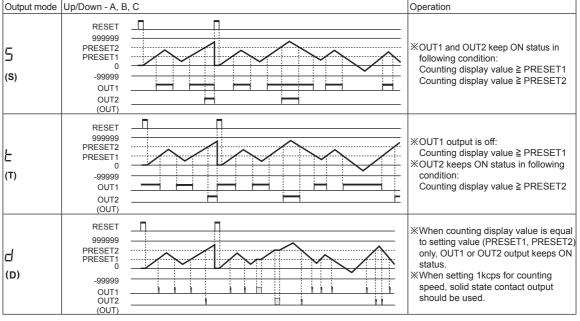
#### One-shot output (0.01 to 99.99 sec.) One-shot output Retained output **■** Output Operation Mode (Counter) Retained output Input mode Output Operation mode Up, Up-1, 2 Down, Down-1, 2 Up/Down A, B, C RESET 999999 PRESET2 ※After count-up, counting display F value increases or decreases until PRESET1 reset signal is applied and retained (F) output is maintained. OUT1 OUT2 П П П П (OUT) П П П RESET 999999 PRESET2 ※After count- up, counting display value and retained output are n PRESET1 maintained until reset signal is (N) applied. OUT1 OUT2 П (OUT) П П RESET When count-up, counting display value 999999 will be reset and count simultaneously. PRESET2 XOUT1 retained output will be off after Ľ PRESET1 OUT2 one- shot time. (C) XThe one-shot output time of OUT1 OUT1 one-shot output time is operated OUT2 gardless of OUT2 output. (OUT) XAfter count-up, counting value П RESET display is reset after one-shot 999999 output time of OUT2 and it counts PRESET2 simultaneously. PRESET1 XOUT1 retained output will be off after 0 (R) OUT2 one-shot time. OUT1 XOUT1 one-shot output time is operated OUT2 (OUT) regardless of OUT2 output ※After count-up, counting display RESET 999999 value increases or decreases until PRESET2 RESET input is applied. PRESET1 XOUT1 retained output is off after (K) OUT2 one-shot time. OUT1 XOUT1 one-shot output time is operated OUT2 regardless of OUT2 output. (OUT) ※After count-up, counting display value is maintained while OUT2 output is on. Counting value is internally reset and RESET 999999 counts simultaneously. When OUT2 output is off, displays counting value while OUT2 is ON, PRESET2 p PRESET<sup>2</sup> and it increases or decreases (P) XOUT1 retained output is off after OUT1 OUT2 one-shot time. OUT2 XOUT1 one-shot output time is operated regardless of OUT2 output (OUT) ┚ RESET XAfter count-up, counting display 999999 PRESET2 value increases or decreases during OUT2 one-shot time q PRESET1 XOUT1 retained output is off after n (Q) OUT2 one-shot time. OUT1 XOUT1 one-shot output time is operated OUT2 regardless of OUT2 output. (OUT) П Д RESET ※After count-up, counting display 999999 value and OUT1 retained output PRESET2 Я PRESET1 are maintained until RESET input is applied (A) OUT1 XOUT1 one-shot output time is operated regardless of OUT2 output. OUT2 (OUT)

\*\*The single preset type output (OUT) is operated as OUT2 of dual preset type. \*\*OUT1 output could be set to 0 in all modes and 0 value output turns ON.

<sup>※</sup>OUT2 output could not set to 0 in C[[ ], R[- ], P[P] or Q[P] output mode.

## Output Operation Mode (Counter)

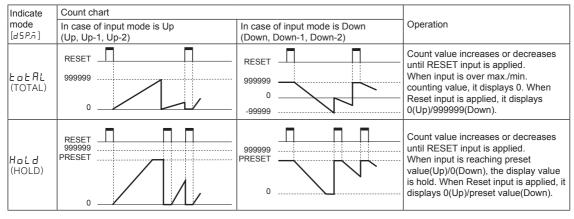




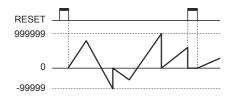
- XThe single preset type output (OUT) is operated as OUT2 of dual preset type.
- ※The dual preset model OUT1 output is operated as one-shot or retained output. (except 5, ₺, ₼ mode)
- XOUT1 output could be set to 0 in all modes and 0 value output turns ON.
- $\times$ OUT2 output could not set to 0 in C[[], R[-], P[P] or Q[9] output mode.

## ■ Counter Operation Of The Indicator (CT6S-I, CT6Y-I, CT6M-I)

XOnly displays on indicator models



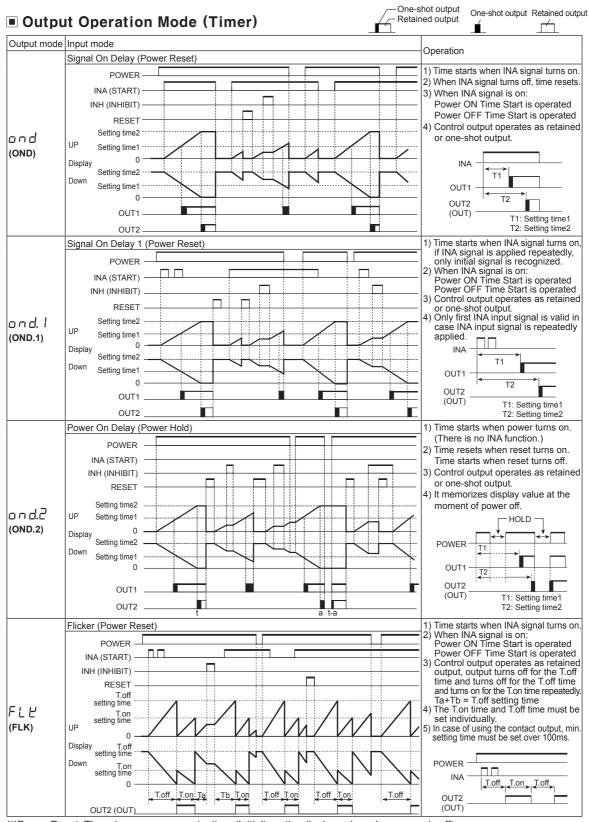
• In case of the Command input [Ud - R], Individual input [Ud - b], Phase difference input [Ud - E] mode.



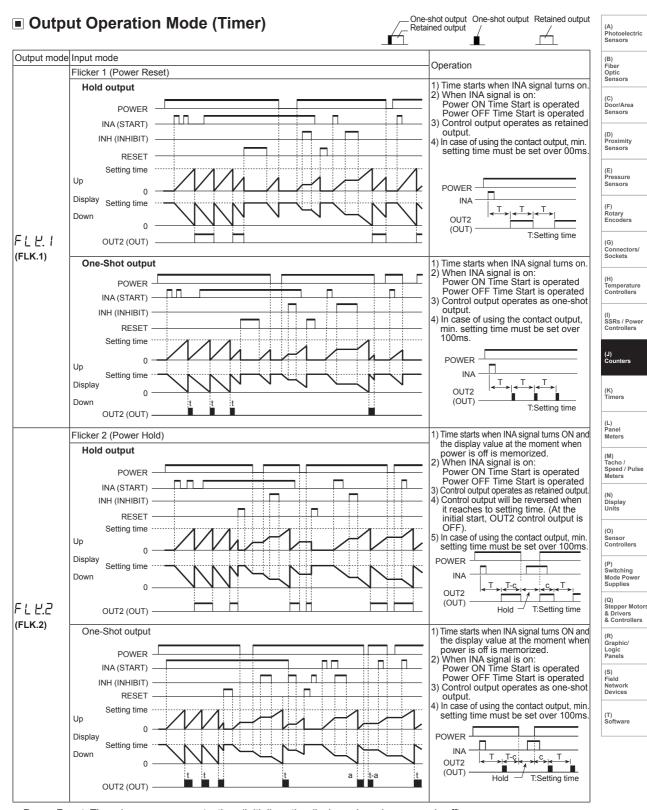
※In case of UP/DOWN [มd-月, มd-Ь, มd-[] input mode, indication mode [d5P.5] of the configuration is not displayed.

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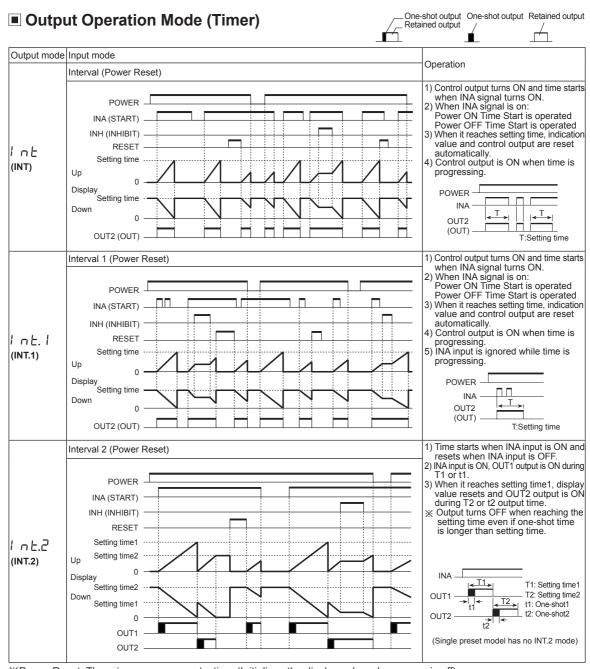
Setting mode	How to set	(B)
Counter/Timer	EoUn ← → ŁI ñE   **EoUn: COUNTER ŁI ñE: TIMER	Fiber Optic Sensors
Timer range Hอปรากิป ก/5EC	● 6digit type    SEL	Door/Area Sensors  (D) Proximity Sensors  (E) Pressure Sensors  (F) Rotary Encoders  (H) Temperatur Controllers  (I) SSRs / Pow Controllers
UP/DOWN mode		(K) Timers
Indication mode d 5 ค.คั	*Used for the indicator only.  **EoERL → HoLd → onE.d	(L) Panel Meters (M) Tacho / Speed / Pul
Memory protection d R Ŀ R		(N) Display Units
Output mode อ ป ะ.กั	ond ←> ond.1 ←> ond.2 ←> FLY.4 →> FLY.2 ←> 1 nt   ↑  1 nt 0 ←> nFd.1 ←> nFd ←> oFd ←> 1 nt.2 ←> 1 nt.1	(O) Sensor Controllers
OUT2 output time	<ul> <li></li></ul>	(P) Switching Mode Powe Supplies (Q) Stepper Mo
oUtc	XSetting range: 0.01 to 99.99sec.  XHaLd is displayed by pressing  key 4 times.	& Drivers & Controlle
OUT1 output time		Graphic/ Logic Panels (S) Field Network
Input logic		(T) Software
Input signal time	**CTS/CTY: Set min. external INA, INH, RESET signal width.  **CTM: Set min. external INA, RESET, INHIBIT,  BATCH RESET signal width.	
Lock key	LoFF ← LoC.1	



※Power Reset: There is no memory protection. (Initializes the display value when power is off) Power Hold: There is memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

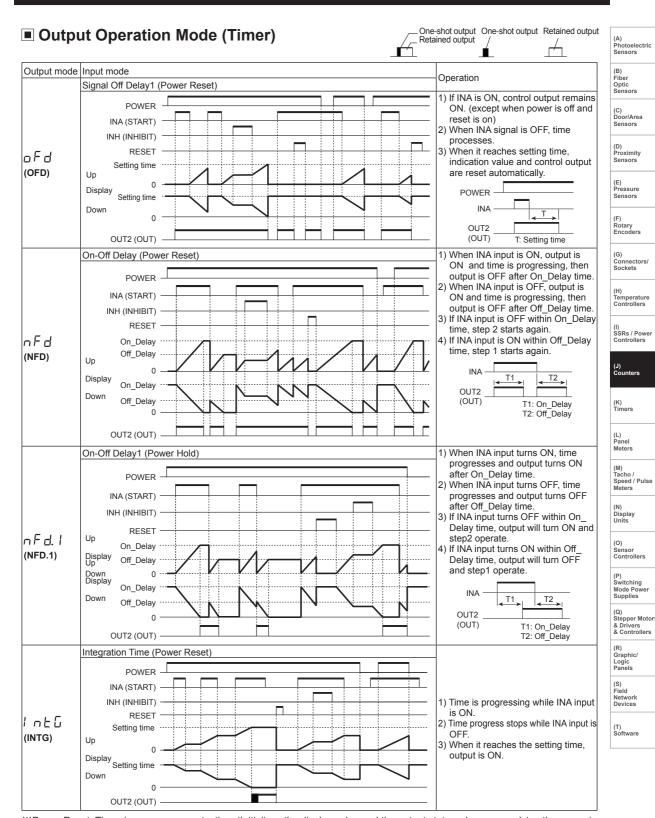


※Power Reset: There is no memory protection. (Initializes the display value when power is off)
Power Hold: There is memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)



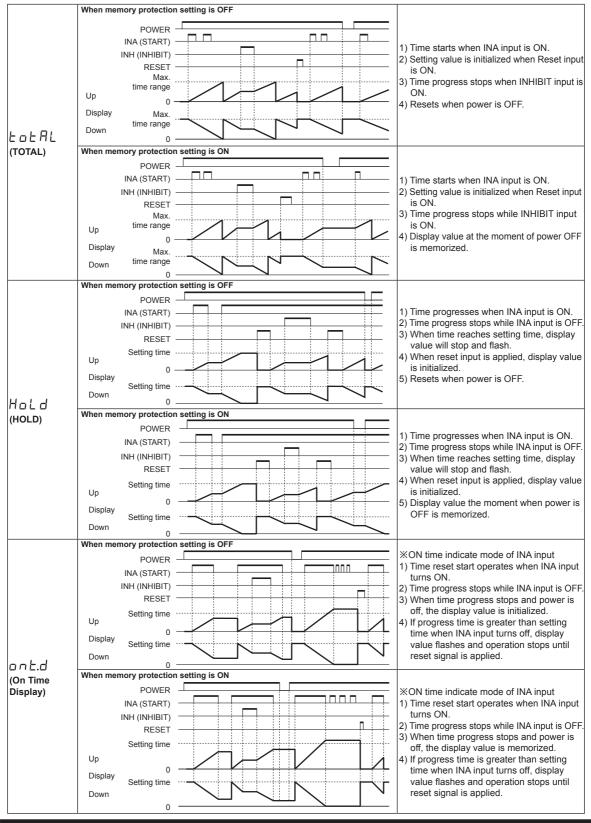
※Power Reset: There is no memory protection. (Initializes the display value when power is off)
Power Hold: There is memory protection. (Memorizes the display value at the moment of power off, indicates the memorized display value when power is resupplied.)

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※Power Reset: There is no memory protection. (Initializes the display value and the output status when re-supplying the power.)
Power Hold: There is memory protection. (It memorizes the status of power off. When re-supplying the power, it returns the memorized display value and the output status.)

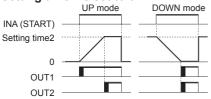
## ■ Timer Operation Of The Indicator (CT6S-I, CT6Y-I, CT6M-I)



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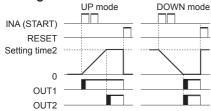
## ■ Timer '0' Time Setting

- O Available output operation mode to set '0' time setting and, and, l, and, l, nFd, nFd, l
- Operation according to output mode (at 0 time setting)
- 1) OND (Signal ON Delay) mode [and]
- Setting time1 is set to 0



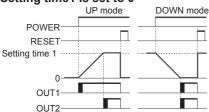
2) OND.1 (Signal ON Delay 1) mode [and. 1]

• Setting time1 is set to 0



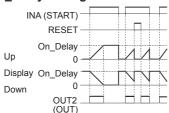
3) OND.2 (Power ON Delay2) mode [and.2]

• Setting time1 is set to 0



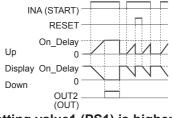
4) NFD (ON-OFF Delay) mode [nFd]

• OFF Delay setting time is set to 0

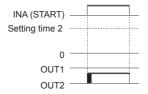


5) NFD.1 (ON-OFF Delay1) mode [nFd.1]

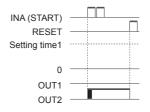
OFF\_Delay setting time is set to 0



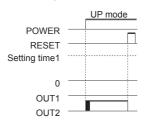
• Setting time2 is set to 0



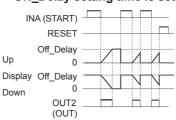
• Setting time2 is set to 0



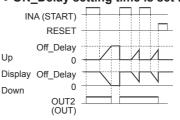
• Setting time2 is set to 0



• ON\_Delay setting time is set to 0



• ON\_Delay setting time is set to 0



○ Setting value1 (PS1) is higher than Setting value2 (PS2)

OND[and], OND.1[and.1] or OND.2[and.2] output mode

- UP mode: When the timer setting value1 is greater than the setting value 2, OUT1 output does not turn ON.
- DOWN mode: When the timer setting value1 is greater than the setting value 2, OUT1 output does not turn ON.
   If the setting value 1 is same as the setting value2 and START signal is applied, OUT1 output turns ON immediately.

(A) Photoelectric Sensors

(B) Fiber Optic

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G) Connectors/ Sockets

(H) Temperature Controllers

(I) SSRs / Powe Controllers

#### (J) Counters

(K) Timers

(L) Panel Meters

(M) Tacho / Speed / Puls

> (N) Display

O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software

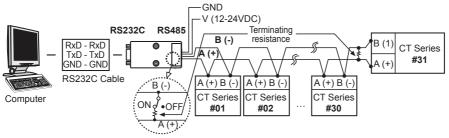
## Communication Mode

## Parameter setting

(MD key: To select setting mode, ✓ or ⋌ key: To change setting value)

Setting mode	How to set						
Com. address	<ul> <li></li></ul>						
Com. speed [6 P 5]	24 ←→ 48 ←→ 96 ←→ 192 ←→ 384 ※24	24 ←→ 48 ←→ 95 ←→ 192 ←→ 384					
Com. parity [Pィヒソ]	nonE ← → EuEn ← → odd	nanE ← → EuEn ← → add					
Com. stop bit [5 £ P]	1 ← → 2	I ←→ 2					
		XSetting range according to com. speed.					
	To shift flashing digits position of com.	2400bps   16ms to 99ms					
esponse waiting time	response waiting time.	4800bps 8ms to 99ms					
[r 5 4.t ]		9600bps 5ms to 99ms					
[ J _ L ]	value.	19200bps 5ms to 99ms					
		38400bps 5ms to 99ms					
Com. write	EnR ← → dl 5R						

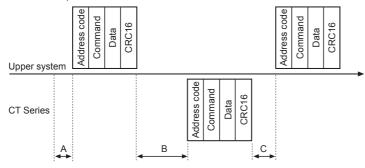
### O Application of system organization



XIt is recommended to use communication converter, RS485 to Serial converter (SCM-38I, sold separately), USB to RS485 converter (SCM-US48I, sold separately). Please use a proper twist pair for RS485 communication.

#### Communication control ordering

- 1. The communication method is Modbus RTU (PI-MBUS-300-REV.J).
- 2. After 1sec. of power supply into the high order system, it starts to communicate.
- 3. Initial communication will be started by the high order system. When a command comes out from the high order system, CT Series will respond.



 $XA \rightarrow Min.$  1sec. after applying power

- B → 7 38400bps: Approx. 1ms. 19200bps: Approx. 2ms.
  - - 9600bps: Approx. 4ms.
    - 4800bps: Approx. 8ms.
  - 2400bps: Approx. 16ms.
- C → Min. 20ms

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#### O Communication command and block

The format of query and response

### 1) Read Coil Status (Func 01 H), Read Input Status (Func 02 H)

#### • Query (Master)

Slave Address		Starting Address				Error Check (CRC 16)	
		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
1.							

CRC 16

#### • Response (Slave)

Slave Address	Function	Byte	Data	Data		Error Ch (CRC 10	
Address		Count				Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte

**CRC 16** 

## 2) Read Holding Registers (Func 03 H), Read Input Registers (Func 04 H)

#### • Query (Master)

Slave Address	Function	Starting Address		INO of Points		Error Check (CRC 16)	
		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte

CRC 16

#### • Response (Slave)

S	Slave	Function 1Byte	Byte	Data		Data		Data		Error (CRC	Check 16)
A	uuress		Count	High	Low	High	Low	High	Low	Low	High
11	Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte

CRC 16

#### 3) Force Single Coil (Func 05 H)

#### Query (Master)

Slave Address		Coil Address		Force Data		Error Check (CRC 16)	
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
						i	

CRC 16

#### Response (Slave)

	Slave Address	Function	Coil Address		Force Data		Error Check (CRC 16)	
			High	Low	High	Low	Low	High
	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
ï								

CRC 16

## 4) Preset Single Register (Func 06 H)

#### Query (Master)

	Slave	Function	Register Address		Preset [	Data	Error Check (CRC 16)	
	Address		High	Low	High	Low	Low	High
	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
i							ı	

CRC 16

#### • Response (Slave)

Slave	F	Register Address		Preset Data		Error Check (CRC 16)	
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte

CRC 16

#### 5) Preset Multiple Registers (Func 10 H)

#### • Query (Master)

Slave Address	Eunction	Starting Address				Byte Count			Data		Error Check (CRC 16)	
		High	Low	High	Low		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte
1-											1	

CRC 16

### Response (Slave)

Slave	Eunction	Starting Address		No of Register		Error Check (CRC 16)	
Address		High	Low	High	Low	Low	High
1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte	1Byte

**CRC 16** 

#### 6) Application

Read Coil Status (Func 01 H)
Master reads OUT2 00002 (0001H) to 00003
(0002H), OUT1 output status (ON: 1, OFF: 0) from
the Slave (Address 01).

#### Query (Master)

Slave	Function			No. of Points		Error Check (CRC 16)	
Address	- unouon	High	Low	High	Low	Low	High
01 H	01 H	00 H	01 H	00 H	02 H	EC H	0B H

On slave side OUT2 00003 (0002H): OFF, OUT1 00002 (0001H): ON

#### Response (Slave)

Slave Address	F	unction	Byte Count	Data	Error Check (CRC 16) Low	High
01 H	0	11 H	01 H	02 H	D0 H	49 H

Read Input Register (Func 04 H)Master reads preset value 21004 (03EBH) to 21005 (03ECH) of counter/timer, Slave (Address 15).

#### • Query (Master)

Slave Address	Function			No of Points		Error Check (CRC 16)	
		High	Low	High	Low	Low	High
0F H	04 H	03 H	EB H	00 H	02 H	00 H	95 H

In case that the present value is 123456 (0001 E240 H) in slave side, 31004 (03EBH): E240 H, 31005 (03ECH): 0001H

#### • Response (Slave)

Slave		Byte Count	Data		Data		Error Check (CRC 16)	
Address			High	Low	High	Low	Low	High
0F H	04 H	04 H	E2 H	40 H	00 H	01 H	E2 H	28 H

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) Door/Area Sensors (D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G) Connectors/ Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

> J) Counters

....

(M) Tacho / Speed / Pulse Meters

Display Units

(O) Sensor Controllers (P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers

(R) Graphic/ Logic Panels

(S) Field Network Devices

> (T) Software

## Modbus Mapping Table

## 1) Reset/Output

No (Address)	Func	Explanation	Setting range	Notice
00001 (0000)	01/05	Reset	0:OFF 1:ON	
00002 (0001)	01	OUT2 output	0:OFF 1:ON	
00003 (0002)	01	OUT1 output	0:OFF 1:ON	
00004 (0003)	01	BATCH output	0:OFF 1:ON	For BATCH output model
00005 (0004)	01/05	BATCH resets	0:OFF 1:ON	For BATCH output model

### 2) Terminal input status

No (Address)	Func	Explanation	Setting range	Notice
10001 (0000)	02	INA input status	0:OFF 1:ON	Terminal input status
10002 (0001)	02	INB input status	0:OFF 1:ON	Terminal input status
10003 (0002)	02	INHIBIT input status	0:OFF 1:ON	Terminal input status
10004 (0003)	02	RESET input status	0:OFF 1:ON	Terminal input status
10005 (0004)	02	BATCH RESET input status	0:OFF 1:ON	Terminal input status

### 3) Product Information

No (Address)	Func	Explanation	Notice
30001 to 30100	04	Reserved	_
30101 (0064)	04	Product number H	Model ID
30102 (0065)	04	Product number L	IVIOGEI ID
30103 (0066)	04	Hardware version	_
30104 (0067)	04	Software version	—
30105 (0068)	04	Model no. 1	"CT"
30106 (0069)	04	Model no. 2	"6M"
30107 (006A)	04	Model no. 3	"-2"
30108 (006B)	04	Model no. 4	"PT"
30109 (006C)	04	Reserved	
30110 (006D)	04	Reserved	
30111 (006E)	04	Reserved	
30112 (006F)	04	Reserved	
30113 (0070)	04	Reserved	_
30114 (0071)	04	Reserved	
30115 (0072)	04	Reserved	
30116 (0073)	04	Reserved	
30117 (0074)	04	Reserved	
30118 (0075)	04	Coil Status Start Address	0000
30119 (0076)	04	Coil Status Quantity	_
30120 (0077)	04	Input Status Start Address	0000
30121 (0078)	04	Input Status Quantity	_
30122 (0079)	04	Holding Register Start Address	0000
30123 (007A)	04	Holding Register Quantity	
30124 (007B)	04	Input Register Start Address	0064
30125 (007C)	04	Input Register Quantity	_

### 4) Monitoring data

No (Address)	Func	Explanation	Setting range	Notice	
		BA.O LED display status	0:OFF 1:ON	Bit 5	
		OUT2 LED display status	0:OFF 1:ON	Bit 6	
		OUT1 LED display status	0:OFF 1:ON	Bit 7	
		BA.S LED display status	0:OFF 1:ON	Bit 10	
31001 (03E8)	04	LOCK LED display status	0:OFF 1:ON	Bit 11	
		PS2 LED display status	0:OFF 1:ON	Bit 12	
		PS1 LED display status	0:OFF 1:ON	Bit 13	
		TMR LED display status	0:OFF 1:ON	Bit 14	
		CNT LED display status	0:OFF 1:ON	Bit 15	
31002 (03E9)	04	Present value of BATCH	0 to 999999	For BATCH output	
31003 (03EA)	•	counter	0 10 000000	model	
31004 (03EB)			Counter 6digit type: -99999 to		
31005 (03EC)	04	Present value of counter/timer	4digit type: -999999 4digit type: -999 to 9999 Timer: Within time setting range	Use counter and timer in common	
31006 (03ED)	04	Display unit	Counter: decimal point of display value Timer: Time range	Counter: 40058 Data Timer: 40102 Data	
31007 (03EE)			Counter 6digit type: -99999 to	Llaa aquatar	
31008 (03EF)	04	PS (2) setting value	999999 4digit type: -999 to 9999 Timer: Within time setting range	Use counter and timer in common	
31009 (03F0)			Counter 6digit type: -99999 to	Use counter	
31010 (03F1)	04	PS1 setting value	999999 4digit type: -999 to 9999 Timer: Within time setting range	and timer in common	
31011 (03F2)	04	Setting value	0 to 999999	Use counter and timer	
31012 (03F3)			0 10 33333	in common	
31013 (03F4)	04	Checking the input logic	0: NPN, 1: PNP		

## • Date format of 31001 (03E8) address bit

	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit4	Bit 3	Bit 2	Bit 1	Bit 0
	CNT	TMR	PS1	PS2	LOCK	BA.S	_	_	OUT1	OUT2	BA.O	_	_	_	_	-
ĺ	0 or 1	0	0	0 or 1	0 or 1	0 or 1	0	0	0	0	0					

※2 Words data format: Upper data has high number address. E.g.)31004: Present Value (Low Word), 31005: Present Value (High Word)

### 5) Preset value setting group

No (Address)	Func	Explanation	Setting range	Notice
40001 (0000)	03	PS2 setting value	Counter	Use counter and timer
40002 (0001)	06 16	PS setting value	6digit type: 0 to 999999	in common
40003 (0002)	03 06	PS1 setting	4digit type: 0 to 9999 Timer: Within time	Use counter and timer
40004 (0002)	16	value	setting range	in common
40005 (0004)		BATCH	0 to 999999	Use counter
40006 (0005)	06 16	counter setting value	0 10 999999	and timer in common

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## 6) Function setting mode (Counter group)

6) Function	setting	mode (Counter gro	• *	(A)
No (Address)	Func	Explanation		Photoelectric Sensors
40051 (0032)	03/06/16	Counter/Timer[[-+]	1: Lollo 1: El ōE Use counter and timer in common	
40052 (0033)	03/06/16	Input mode[! n]	0: UP	(B) Fiber Optic Sensors (C) Door/Area
40053 (0034)	03/06/16	Indication mode[d1 5 n]	4: dn - 1 0: E a L R L 1: H a L d For the indicator	Sensors
40054 (0035)	03/06/16	Output mode[allEn]	0.7 0.7	(D) Proximity Sensors
40055 (0036)	03/06/16	Maximum counting speed[[P5]]	0: I 2: IE 4: IDE	(E) Pressure Sensors
40056 (0037)	03/06/16	OUT2 (OUT) output time	000 / to 9999 unit: ×10ms	
40057 (0038)	03/06/16	OUT1 Output time		(F)
40058 (0039)	03/06/16	Decimal point[dP]		Rotary Encoders
40059 (003A)	03/06/16	Min. reset time[-5+]	0:   1: 2 0 unit: ms	(G)
40060 (003B)	03/06/16	Prescale decimal point position [5 [ L.d ]		Connectors/ Sockets
40061 (003C) 40062 (003D)	03/06/16	Prescale value[5 [ L ]	Adjoint type: 000 L to 0000	(H) Temperature Controllers
40063 (003E) 40064 (003F)	03/06/16	Start value[5 + r + ]	6digit type: 000000 to 999999 Connected with decimal	
40065 (0040)	03/06/16		O.E.L.F. I.FEL OSE Counter and timer	(I) SSRs / Power Controllers
40066 (0041)	03/06/16	Lock key[Lo[H]	0: L.o F	

7) Function setting mode (Timer group)

No (Address)	Func	Explanation	Setting range	Notice	
40101 (0064)	03/06/16	Counter/Timer[[-+]	0: EoUn 1: E! ñE	Use counter and timer in common	
			4digit type		
		Time reads	0: 0.001s to 9.999s 5: 0.1m to 999.9m 1: 0.01s to 99.99s 6: 1m to 9999m 2: 0.1s to 999.9s 7: 1m to 99959m 3: 1s to 9999s 8: 1h to 9999h 4: 1s to 99m59s		
40102 (0065)	03/06/16	Time range	6digit type	_	
(,		[	0: 0.001s to 999.999s 6: 1s to 9999m59s 7: 1m to 99999.9m 2: 0.1s to 99999.9s 8: 1m to 999999m 3: 1s to 9999999 9: 1s to 99h59m59s 4: 0.01s to 99m59.9s 10: 1m to 99999.9h 11: 0.1h to 99999.9h		
40103 (0066)	03/06/16	UP/Down mode	0: UP 1: dn	<u> </u>	
40104 (0067)	03/06/16	Output mode	0: ond 3: FLE 7: I nE. I 10: nFd 1: ond I 4: FLE. I 8: I nE. 2 11: nFd. I 2: ond 2 5: FLE. 2 9: oFd 12: I nE. G	_	
40105 (0068)	03/06/16	OUT2 (OUT) Output time	0000 to 9999 (0: Hold)	unit: ×10ms	
40106 (0069)	03/06/16	OUT1 Output time	0000 to 9999 (0: Hold)	unit: ×10,ms	
40107 (006A)	03/06/16	Input signal time[I n E]	0: 1 1: 20	unit: ms	
40108 (006B)	03/06/16	Memory protection [d R L R]	0: [Lr 1: r E [	Use counter and timer in common	
40109 (006C)	03/06/16	Lock key[Lo[H]	0: L.oFF 1: LoC. 1 2: LoC.2 3: LoC.3	Use counter and timer in common	
40110 (006D)	03/06/16	ndication mode [d 5 P.ñ]	O: totAL 1: Hold 2: ont.d	For the indicator	

(C) Door/Area Sensors (D) Proximity Sensors (E) Pressure Sensors (I) SSRs / Power Controllers (P) Switching Mode Power Supplies (R) Graphic/ Logic Panels

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#### 8) Function setting mode (Communication group)

No (Address)	Func	Explanation	Setting range	Notice
40151 (0096)	03/06/16	Com. address [Addr]	1 to 127	<del>-</del>
40152 (0097)	03/06/16	Com. speed [b P 5 ]	0:24 1:48 2:96 3:192 4:384	unit: ×100bps
40153 (0098)	03/06/16	Com. parity [Pィヒリ]	0:nonE 1:EuEn 2:odd	
40154 (0099)	03/06/16	Stop bit [5 £ P]	0: / 1: 2	<del></del>
40155 (009A)	03/06/16	Response waiting time [-54.6]	05 to 99	unit: ms
40156 (009B)	03/06/16	Com. writing [[añ.]]	0:EnR 1:d/5R	_

## Exception processing

When communication error occurs, the highest bit of received function is set to 1, then sends response command and transmits exception code.

Slave Address	Function+80H	Exception Code	Error Check (CRC16)		
Slave Address	T direction+oori	Lxception code	Low	High	
1Byte	1Byte	1Byte	1Byte	1Byte	

- Illeegal Function (Exception Code: 01H): Not supporting command
- Illegal Data Address (Exception Code: 02H): Mismatch between the number of asked data and the number of transmittable data.
- Illegal Data Value (Exception Code: 03H): Mismatch between asked the number of data and transmittable the number of data in device
- Slave Device Failure (Exception Code: 04H): Command is processed incorrectly.

#### Example)

Master reads output status (ON:1, OFF:0) of non existing coil 01001 (03E8 H) from Slave (Address17).

#### Query (Master)

	Slave Address	Function	Starting Address		No. of Points		Error Check (CRC16)	
			High	Low	High	Low	Low	High
	11H	01H	03H	E8H	00H	01H	##H	##H

### • Response (Slave)

Slave Address	Function + 80H	Exception Code	Error Check (CRC16)		
Slave Address	FUNCTION + OUT	Exception Code	Low	High	
11H	81H	02H	##H	##H	

## Read And Write Of Parameter Value Using Communication

#### Read of the parameter area

00002 (OUT2), 00003 (OUT1), 00004 (BA, 0), 10001 to 10005 (Terminal input), 30101 to 30125 (Product information), 31001 to 31013 (Monitoring data)

#### Read and write of the parameter area

00001 (Reset starts), 00005 (BATCH Reset starts), 40001 to 40006 (Setting value saving group), 40051 to 40066 (Counter setting group), 40101 to 40110 (Timer setting group).

40151 to 40156 (Communication setting group)

#### Read of communication

Read parameter value using communication. (Function: 01H, 02H, 03H, 04H) It is able to read communication regardless of permitting/prohibiting communication writing.

## O Communication write

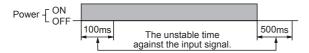
Change parameter value using communication. (Function: 05H, 06H, 10H)

- When changing the parameter setting value of '■ Function setting mode Counter group' or '■ Function setting mode
   Timer group' using communication, reset indication will flash in 3 sec. and display value will be reset. (Counting
   display value and progress time before changing parameter setting value are not saved.)
- When changing the parameter setting value of '
   Preset value setting group' or '
   Function setting mode
   Communication group' using communication, counting display value or progress time will not be reset.
- In prohibit writing communication setting ([a-ā, ] = 1:d! 5A), a write command does not process.
- If setting value beyond the setting range, this setting value is substituted for the value within the setting range and then memorized.

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## Proper Usage

## **○** The power ON/OFF



Power voltage rises for 100ms after power on and falls for 500ms after power off. Therefore be sure to apply input signal after 100ms and power turns on again after 500ms when power turns off.

 Be sure to use insulated and resistive voltage /current or Class2 supply power device to input 24VAC/24-48VDC power supply model.

## Input signal line

- Use as short a cable from the sensor to this unit as possible.
- Use shielded cable for long input line.
- Wire as separating input line from the power line.

## When selecting input logic

Be sure that supply power is off when selecting input logic, then select logic input according to input logic changing method.

# Contact count input (When it is used as Counter)

If apply contact input at high speed mode (1k, 5k, 10k), it may cause miscount by chattering.

Therefore set low speed mode (1cps or 30cps) at contact input.

- When test dielectric voltage and insulation resistance of the control panel with this unit installed.
- Please isolate this unit from the circuit of control panel.
- Please make all terminals of this unit short-circuited.

### O Do not use below places.

- Place where there is severe vibration or impact.
- Place where strong alkalis or acids are used.
- Place where there is direct ray of the sun.
- Place where strong magnetic field or electric noise is generated.
- This unit may be used in the following environments.
- Indoor
- Altitude: Under 2,000m
- Pollution degree 2
- Installation category II

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

> (C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G) Connectors/ Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

#### (J) Counters

(K) Timers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

> (N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software